

$$\hat{H} = \underbrace{\frac{\hat{p}^2}{2m}}_{\hat{H}_0} + Ax^4 - F(t)x$$

$$\hat{H}_{2\text{-level}} = \begin{pmatrix} \langle \phi_1 | \hat{H}_0 | \phi_1 \rangle & \langle \phi_1 | \hat{H}_0 | \phi_2 \rangle \\ \langle \phi_2 | \hat{H}_0 | \phi_1 \rangle & \langle \phi_2 | \hat{H}_0 | \phi_2 \rangle \end{pmatrix}$$

$$E_j \phi_j = \hat{H}_0 \phi_j$$

$$X_{2\text{-level}} = \langle \phi_1 | x | \phi_2 \rangle \begin{pmatrix} |\phi_1\rangle \langle \phi_2| & -|\phi_2\rangle \langle \phi_1| \end{pmatrix}$$

$$\frac{d}{dt} \langle X_{2\text{-level}} \rangle = \frac{\langle \hat{p}_{2\text{-level}} \rangle}{m} \quad \hat{p}_{2\text{-level}} = m \langle \phi_1 | x | \phi_2 \rangle \omega_0 \begin{pmatrix} |\phi_1\rangle \langle \phi_2| & -|\phi_1\rangle \langle \phi_2| \end{pmatrix}$$

$$\frac{d}{dt} \langle \hat{p}_{2\text{-level}} \rangle = -m\omega_0^2 \langle X_{2\text{-level}} \rangle + \frac{2m\omega_0}{\hbar} \langle \phi_1 | x | \phi_2 \rangle^2 F(t) \frac{(|c_1|^2 - |c_2|^2)}{(|c_1|^2 - |c_2|^2)}$$

Quartic Model

$$\frac{d}{dt} \langle \hat{x} \rangle = \frac{\langle \hat{p} \rangle}{m}$$

2-level system:

$$\frac{d}{dt} \langle X_{2\text{-level}} \rangle = -\langle 4Ax^3 \rangle + F(t)$$

$$\frac{d}{dt} \langle \hat{p} \rangle = -\langle 4Ax^3 \rangle + F(t)$$

$$\frac{d}{dt} \langle \hat{p}_{2\text{-level}} \rangle = -m\omega_0^2 \langle X_{2\text{-level}} \rangle + \frac{\langle \phi_1 | x | \phi_2 \rangle^2}{\langle \phi_1 | x | \phi_2 \rangle^2} F(t) \frac{(|c_1|^2 - |c_2|^2)}{(|c_1|^2 - |c_2|^2)}$$

Fixed SHO

$$\frac{d}{dt} \langle x \rangle = \frac{\langle \hat{p} \rangle}{m}$$

$$\frac{d}{dt} \langle \hat{p} \rangle = -m\omega_0^2 \langle x \rangle + F(t)$$

if  $|c_1|^2 = 1$

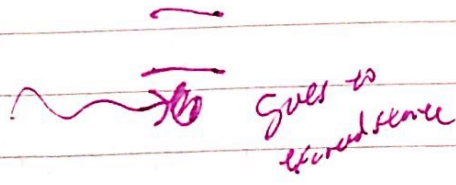
Restoring force

- $\langle 4Ax^3 \rangle$  quartic well
- $m\omega_0^2 \langle x \rangle$  2-level system

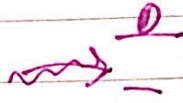
$$\psi(x,t) = \sum_{i=1,2} c_i(t) \phi_i(x) \Rightarrow \langle x \rangle = \langle \psi | x | \psi \rangle = \langle \phi_1 | x | \phi_2 \rangle (c_1^* c_2 + c_2^* c_1)$$

$$\Rightarrow 4A \langle \phi_1 | x^3 | \phi_2 \rangle (c_1^* c_2 + c_2^* c_1)$$

$$-4A \langle \phi_1 | x^3 | \phi_2 \rangle = -m\omega_0^2 \langle \phi_1 | x | \phi_2 \rangle$$



gives to forced motion



next atom pushes back so field is stopped

→ Random laser  
laser starts  
very dense

$$F(t) (|G|^2 - |C|^2)$$

push back on whatever pushing it.

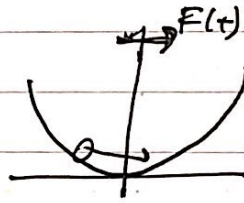
$$|C|^2 > |G|^2$$

⇒ population inversion

amplitude vibrations

→ make lasers.

Add loss, friction



$$\hat{H} = |\phi_1\rangle H_1 \langle \phi_1| + |\phi_1\rangle H_{12} \langle \phi_2| + |\phi_2\rangle H_{21} \langle \phi_1| + |\phi_2\rangle H_2 \langle \phi_2|$$

$$\frac{d}{dt} x(t) = \frac{p(t)}{m}$$

$$\frac{d}{dt} p(t) + \frac{p(t)}{\tau} = -m\omega_0^2 x(t) + F(t)$$

decay to friction in classical model

$$\frac{d}{dt} \langle x_{2\text{-level}} \rangle = \frac{\langle \hat{p}_{2\text{-level}} \rangle}{m}$$

$$\frac{d}{dt} \langle p_{2\text{-level}} \rangle + \frac{\langle \hat{p}_{2\text{-level}} \rangle}{\tau} = -m\omega_0^2 \langle x_{2\text{-level}} \rangle + ( ) F(t)$$

2 level model also used for spin systems